D3XX for Linux 1.0.16

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Jul 18 2024

Introduction

D3XX for Linux/OS-X is an userspace library implemented based on libusb, which provides D3XX compatible APIs on Linux. There are some differences in the implementation APIs for Windows and Linux, which are listed below the API matrix.

	Windows	Linux/OS-X
Asynchronous API	Required for high throughput since it's not a buffered design, to keep multiple URB requests in the queue	Not required. Library's internal threads will keep multiple URB requests in the queue.
Data loss	Host will hang when `FT_ReadPipe` read 8K but FIFO master only returns 1K and no more data's coming, abort procedure is required to recovery from hang but 1K data will be lost	Set `dwURBBufferSize` of `FT_SetTransferParams` to 1024 for this situation to avoid both data loss and hang issue
Notification	Use `FT_ReadPipe` to read exactly the same amount of data reported by notification	Use `FT_ReadPipeEx` with timeout to get any data length, set timeout to 0 to read from library buffer only

libftd3xx uses an unmodified version of libusb which is distributed under the terms of the LGPL.

History

- 1.0.15
  - Added Zero length packet functionality.
  - Removed session write in the WritPipe.
- 1.0.14

- – Fix for memory leak.
- 1.0.13
    - – Fix for double free in AbortPipe. (libusb_free_transfer API is called when transfer callback is invoked)
    - – Added tar file creation for MacOs libraries.

- 1.0.12
    - – Fix for FT_AbortPipe timing issue and crash (removed libusb_free_transfer from FT_AbortPipe API)
    - – Fix for Multi-channel support.
- 1.0.11
    - – libusb1.0.26 update for MacOS.
- 1.0.10
    - – Fix for FT_GetOverlappedResult() API.
    - – Removed unuse code.
- 1.0.9
    - – Removed resubmission of transfer buffer in call-back.
- 1.0.8
    - – Fix for limit of 8 overlap buffers. (Modified libusb_transfer buffer allocation in write and read async functionalities).
    - – Updated the libusb version to 1.0.26
- 1.0.7
    - – Improved the Abort functionality and added Abort recovery Sample code.
    - – Improved the Write Async functionality.
- 1.0.6
    - – FT602 Support added for ARMv8 and ARMv7-32.
- 1.0.5
    - – Fix for the issue with data read in the Notification call back function.
- 1.0.4
    - – Support FT_SetNotificationCallback() API.
    - – Support FT_ClearNotificationCallback() API.
- 1.0.3
    - – Fix the small packet issue with FT_ReadPipeEx API
- 1.0.2
    - – Fix for the issue with data read in 1.0.1. There were some addional data coming in.
- 1.0.1
    - – Fix issue in Async transfer.
- 1.0.0
    - – New Driver
    - – Removed read and write buffering at the library level.
    - – New API's supported.
        - * FT_GetOverlappedResult()
        - * FT_InitializeOverlapped()
        - * FT_ReleaseOverlapped()

* FT_SetStreamPipe()
* FT_ClearStreamPipe()
* FT_AbortPipe()
* FT_ReadPipeAsync()
* FT_WritePipeAsync()
    - Bug fix: FT_SetChipConfiguration() API NULL pointer issue.
    - Support for ARMv6 (hard float) is enabled.
- 0.6.5
    - Bug fix: Fix the read issue for macOs.
- 0.6.4
    - Bug fix: FT_GetDeviceDescriptor() API failure.
    - Support FT_GetInterfaceDescriptor() API.
    - Support FT_GetPipeInformation() API.
- 0.6.3.1
    - Fix Serial number field lengh mismatch
- 0.6.3
    - Add in location ID (locID) for D3XX devices. Based on the bus number and the device address.
- 0.5.28
    - Fix for i686 wrap_memcpy issue.
- 0.5.25
    - Support for ARM Linux Build.
- 0.5.21
    - Bug fix: Ignore failure of update U1 for Revision A device
- 0.5.20
    - Limit maximum URB size to 16KB if Linux kernel version <= 3.3
    - Move workaround for FT600/FT601 Revision A chip from sample code into library
    - Start IN streaming after `FT_ReadPipe()`/`FT_ReadPipeEx()` has been called
- 0.5.17
    - Compiled with Ubuntu 14.04 (GCC 4.8.4) to support SUSE Linux Enterprise Server 11 SP4
    - For static link build, please use Ubuntu 14.04
- 0.5.6
    - Cross compiled with Android NDK R15, targeted to Android 6.0 API level 23
    - Static link to LLVM libc++ runtime
- 0.5.3
    - Compile with GCC 4.9.2, GLIBC 2.19
    - Bug fix: Fix potential session not auto repeated issue
    - API: `FT_GetDeviceInfoList()` will not longer open device if pftHandle is not NULL, which follows Windows Library's implementation
    - API: Filling correct value in pulLengthTransferred of `FT_ControlTransfer()`
- 0.5.0

- – Add Rev B chip support
- 0.4.11
  - – Bug fix: `FT_ReadGPIO()` returns wrong value for Rev A chip
  - – Bug fix: Change return value to FT_OK when `FT_ReadPipe()` and `FT_ReadPipeEx()`'s return value is FT_TIMEOUT and at least 1 byte had been read
- 0.4.10
  - – API: implemented `FT_EnableGPIO() FT_WriteGPIO() FT_ReadGPIO()` for Revision A device
  - – API: implemented `FT_GetDescriptor() FT_GetStringDescriptor() FT_GetDeviceDescriptor() FT_GetConfigurationDescriptor() FT_GetInterfaceDescriptor() FT_GetPipeInformation() FT_ListDevices()`
- 0.4.9
  - – Support Revision B device: request device send ZLP before `FT_ReadPipe()`/`FT_ReadPipeEx()` timeouts
- 0.4.8
  - – Bug fix: multiple channel read/write not working correctly
  - – Remove FT_AddVIDPID() API, stop detecting D3XX devices by using VID/PID anymore
- 0.4.7
  - – Allow NULL parameters for FT_GetDeviceInfoDetail()
- 0.4.6
  - – Stop changing chip configuration in FT_Create(), please remove ENABLENOTIFICATIONMESSAGE_INCHALL and set DISABLE-CANCELSESSIONUNDERRUN in your application
  - – Bug fix: read buffer pointer is not increased which cause data not been copied.
  - – New demo application: file_transfer.cpp which use FT245 loopback to duplicate file.
- 0.4.5
  - – Add workaround for FT600/FT601 Rev.A device to prevent sending control requests when streaming is on, which may cause system hang or failed to create device.
- 0.4.4
  - – Demo application: add new argument to change FIFO mode.
  - – API: implemented `FT_EnableGPIO() FT_WriteGPIO() FT_ReadGPIO() FT_SetGPIOPull()` for Revision B device.
- 0.4.3
  - – First beta release

Installation

```
sudo rm /usr/lib/libftd3xx.so
sudo cp libftd3xx.so /usr/lib/
sudo cp libftd3xx.so. /usr/lib/
```

```
sudo cp 51-ftd3xx.rules /etc/udev/rules.d/
sudo udevadm control --reload-rules
```

Demo application

1. Extract the release package, compile the demo application.

```
make
```

2. Streamer application usage:
   - Arguments: `./stremer <read channel count> <write channel count> [mode]`
     - Mode: 0 = FT245 mode (default), 1 = FT600 mode
   - Examples:
     - FT245 loopback FPGA: `./streamer 1 1`
     - FT600 loopback FPGA: `./streamer 4 4 1`
     - FT245 streaming FPGA (read only): `./streamer 1 0`
     - FT245 streaming FPGA (write only): `./streamer 0 1`
     - FT245 streaming FPGA (read and write): `./streamer 1 1`
     - FT600 streaming FPGA (3 channel read 1 channel write): `./streamer 3 1 1`
   - Please run with root permission if streamer app failed to detect any device.
   - Alternatively you can run the streamer application without installing library: `sh    sudo LD_LIBRARY_PATH=. ./streamer 1 0`
3. File transfer loopback application usage:
   - Arguments: `./file_transfer <src file> <dest files> <FIFO mode/channel count> [loop]`
     - FIFO mode/channel count: 0 = FT245 fifo mode, 1 - 4 FT600 channel count
     - loop: 0 = oneshot (default), 1 = loop forever

Demo application for Android

1. Install CMake and NDK from Android SDK Manager
2. Extract the release package, open `android-build` with your preferred text editor, the content of the file looks like below: `#!/bin/bash ASDK=/usr/local/opt/android-sdk  ANDROID_API_LEVEL=android-23 TMP_DIR=/tmp/d3xx-demo  ARCHS=(arm64-v8a armeabi-v7a armeabi x86_64 x86)  # Set to OFF if dynamic link is preferred STATIC_LINK_TO_D3XX=ON`
3. Change `ASDK` to point to the path of your Android SDK
4. Compile the demo application

```
./android-build
```

4. Run the compiled application on your Android target

```
adb push streamer /data/local/tmp
adb push libftd3xx.so /data/local/tmp
adb shell
su
cd /data/local/tmp
LD_LIBRARY_PATH=. ./streamer 1 1
```

Static link

1. GCC 4.9 or later must be used
2. Link with GCC 4.9.2 C++ static library is required:

```
LIBS = -L . -lftd3xx-static -llibstdc++-static
```

D3XX API matrix

API	Linux	Win	Remark for Linux
FT_CreateDeviceInfoList	I[1]	I	
FT_GetDeviceInfoList	I	I	
FT_GetDeviceInfoDetail	I	I	
FT_ListDevices	I	I	
FT_Create	I	I	
FT_Close	I	I	
FT_WritePipe	I	I	pOverlapped parameter is not supported, internally will call FT_WritePipeEx with timeout option from FT_SetPipeTimeout, default timeout is 1second
FT_ReadPipe	I	I	pOverlapped parameter is not supported, internally will call FT_ReadPipeEx with timeout option from FT_SetPipeTimeout, default timeout is 1second
FT_GetOverlappedResult	I	I	
FT_InitializeOverlapped	I	I	
FT_ReleaseOverlapped	I	I	
FT_SetStreamPipe	I	I	
FT_ClearStreamPipe	I	I	
FT_AbortPipe	I	I	
FT_FlushPipe	I	I	
FT_GetDeviceDescriptor	I	I	
FT_GetConfigurationDescriptor	I	I	Active configuration only
FT_GetInterfaceDescriptor	I	I	Active configuration only
FT_GetStringDescriptor	I	I	
FT_GetPipeInformation	I	I	
FT_GetDescriptor	I	I	

API	Linux	Win	Remark for Linux
`FT_ControlTransfer`	I	I	
`FT_GetVIDPID`	I	I	
`FT_SetGPIO`	X	I	Obsoleted
`FT_GetGPIO`	X	I	Obsoleted
`FT_EnableGPIO`	I	I	
`FT_WriteGPIO`	I	I	
`FT_ReadGPIO`	I	I	
`FT_SetGPIOPull`	I	X	For Rev. B device only
`FT_SetNotificationCallback`	X	I	
`FT_ClearNotificationCallback`	X	I	
`FT_GetChipConfiguration`	I	I	
`FT_SetChipConfiguration`	I	I	
`FT_IsDevicePath`	X	I	Linux doesn't support GUID path
`FT_GetDriverVersion`	I	I	
`FT_GetLibraryVersion`	I	I	
`FT_GetFirmwareVersion`	I	I	
`FT_ResetDevicePort`	I	I	
`FT_CycleDevicePort`	X	I	
`FT_SetPipeTimeout`	I	I	Added to keep compatible with D3XX for Windows 1.2.0.5 RC6. Set 0 to read from /write to library buffer only
`FT_SetTransferParams`	I	X	Must be called before `FT_Create` is called
`FT_ReadPipeEx`	I	X	equivalent to `FT_SetPipeTimeout` + `FT_ReadPipe`. Use FIFO index instead of endpoint to address pipe
`FT_WritePipeEx`	I	X	equivalent to `FT_SetPipeTimeout` + `FT_WritePipe`. Use FIFO index instead of endpoint to address pipe
`FT_ReadPipeAsync`	I	X	Reads data from the pipe. An enhanced version of FT_ReadPipeEx for improved latencies between reads. However to get the maximum benefit, this API should be used asynchronously with FT_SetStreamPipe.
`FT_WritePipeAsync`	I	X	Writes data to the pipe. FT_WritePipeAsync used for asynchronous transfers with FT_SetStreamPipe. However the maximum input buffer size supported for this API is 1 Mega Byte to guarantee the lower latencies.

New Linux only APIs

```c
enum FT_GPIO_PULL {
    GPIO_PULL_50K_PD,
    GPIO_PULL_HIZ,
    GPIO_PULL_50K_PU,
    GPIO_PULL_DEFAULT = GPIO_PULL_50K_PD
};

enum FT_PIPE_DIRECTION {
    FT_PIPE_DIR_IN,
    FT_PIPE_DIR_OUT,
    FT_PIPE_DIR_COUNT,
};

struct FT_PIPE_TRANSFER_CONF {
    /* set to true PIPE is not used, default set to FALSE */
    BOOL fPipeNotUsed;

    /* Enable non thread safe transfer to increase throughput, set this flag
     * if guarantee only single thread access the pipe at a time, default
     * set to FALSE */
    BOOL fNonThreadSafeTransfer;

    /* Concurrent URB request number, 8 by default, set value < 2 to use
     * default value */
    BYTE bURBCount;

    /* 256 by default, set value < 2 to use default value */
    WORD wURBBufferCount;

    /* 32K by default, set value < 512 to use default value */
    DWORD dwURBBufferSize;

    /* 1G by default, used by FT600 and FT601 only, set 0 to use
     * default value */
    DWORD dwStreamingSize;
};

typedef struct _FT_TRANSFER_CONF {
    /* structure size: sizeof(FT_TRANSFER_CONF) */
    WORD wStructSize;

    /* Please refer to struture FT_PIPE_TRANSFER_CONF */
    struct FT_PIPE_TRANSFER_CONF pipe[FT_PIPE_DIR_COUNT];
```

---

[1]Implemented #[^X]: Non-exists

```c
    /* Stop reading next URB buffer if current buffer is not fully filled,
     * default set to FALSE */
    BOOL fStopReadingOnURBUnderrun;

    /* Reserved, set to 0 */
    BOOL fReserved1;

    /* Do not flush device side residue buffer after reopen the
     * device, default set to FALSE */
    BOOL fKeepDeviceSideBufferAfterReopen;
} FT_TRANSFER_CONF;

/* Set transfer parameters for each FIFO channel
 * Must be called before FT_Create is called. Need to be called again
 * after FT_Close(), otherwise default parameters will be used.
 *
 * Default value will be used for each FIFO channel if this function
 * is not been called. Please refer to structure defines for default
 * value.
 *
 * pConf: Please refer to structure FT_TRANSFER_CONF
 * dwFifoID: FIFO interface ID. Valid values are 0-3 which represents
 *           FIFO channel 1-4 for FT600 and FT601 */
FTD3XX_API FT_STATUS FT_SetTransferParams(
        FT_TRANSFER_CONF *pConf,
        DWORD dwFifoID);

/* ReadPipe with timeout
 *
 * dwFifoID: FIFO interface ID. Valid values are 0-3 which represents
 *           FIFO channel 1-4 for FT600 and FT601
 * dwTimeoutInMs: timeout in milliseconds, 0 means return immediately
 *           if no data */
FTD3XX_API FT_STATUS FT_ReadPipeEx(
        FT_HANDLE ftHandle,
        UCHAR ucFifoID,
        PUCHAR pucBuffer,
        ULONG ulBufferLength,
        PULONG pulBytesTransferred,
        DWORD dwTimeoutInMs);

/* WritePipe with timeout
 *
 * dwFifoID: FIFO interface ID. Valid values are 0-3 which represents
 *           FIFO channel 1-4 for FT600 and FT601
```

```
 * dwTimeoutInMs: timeout in milliseconds, 0 means return immediately
 *           if no data */
FTD3XX_API FT_STATUS FT_WritePipeEx(
        FT_HANDLE ftHandle,
        UCHAR ucFifoID,
        PUCHAR pucBuffer,
        ULONG ulBufferLength,
        PULONG pulBytesTransferred,
        DWORD dwTimeoutInMs);


/* Enable GPIOs
 * Each bit represents one GPIO setting, GPIO0-GPIO2 from LSB to MSB
 *
 * dwMask: set bit to 0 to skip the GPIO, 1 to enable the GPIO
 * dwDirection: set bit to 0 for input, 1 for output */
FTD3XX_API FT_STATUS FT_EnableGPIO(
        FT_HANDLE ftHandle,
        DWORD dwMask,
        DWORD dwDirection
        );


/* Set GPIO level
 * Each bit represents one GPIO setting, GPIO0-GPIO2 from LSB to MSB
 *
 * dwMask: set bit to 0 to skip the GPIO, 1 to enable the GPIO
 * dwDirection: set bit to 0 for low, 1 for high */
FTD3XX_API FT_STATUS FT_WriteGPIO(
        FT_HANDLE ftHandle,
        DWORD dwMask,
        DWORD dwLevel
        );


/* Get level of all GPIOs
 * Each bit represents one GPIO setting, GPIO0-GPIO2, RD_N, OE_N from
 * LSB to MSB */
FTD3XX_API FT_STATUS FT_ReadGPIO(
        FT_HANDLE ftHandle,
        DWORD *pdwData
        );


/* Set GPIO internal pull resisters
 * dwMask: Each bit represents one GPIO setting, GPIO0-GPIO2 from
 * LSB to MSB
 * dwPull: Each two bits represents one GPIO setting, GPIO0-GPIO2 from
 * LSB to MSB
 *
```

```
 * dwMask: set bit to 0 to skip the GPIO, 1 to enable the GPIO
 * dwPull: refer to enum FT_GPIO_PULL */
FTD3XX_API FT_STATUS FT_SetGPIOPull(
        FT_HANDLE ftHandle,
        DWORD dwMask,
        DWORD dwPull
        );
```

Notes

1. Kernel 3.3 and older limitations

   - Maximum URB size cannot be larger than 16384 bytes
   - Kernel may not be able to allocate more than 60 of concurrent URB requests, please refer to kernel source

   The following code example shows how to cope with the limits,

   ```
   static void old_kernel_workaround(void)
   {
       FT_TRANSFER_CONF conf;

       memset(&conf, 0, sizeof(FT_TRANSFER_CONF));
       conf.wStructSize = sizeof(FT_TRANSFER_CONF);
       conf.pipe[FT_PIPE_DIR_IN].bURBCount = 7;
       conf.pipe[FT_PIPE_DIR_OUT].bURBCount = 7;
       conf.pipe[FT_PIPE_DIR_IN].dwURBBufferSize = 16384;
       conf.pipe[FT_PIPE_DIR_OUT].dwURBBufferSize = 16384;
       for (DWORD i = 0; i < 4; i++)
           FT_SetTransferParams(&conf, i);
   }
   ```

2. Please call `FT_CreateDeviceInfoList` again after `FT_ResetDevicePort` is been called, because the device is disconnected after port reset.

   ```
   FT_ResetDevicePort(handle);
   FT_Close(handle);
   FT_CreateDeviceInfoList(&count);
   ```

3. Rev.A chip failed to get 1K aligned data issue

   When FIFO master's last write is 1K aligned data, and master stop writing after this, part of the 1K aligned data may stuck in the host URB buffer, and application will not be able to receive it, until fifo master start to write again.

   If your application hits this special case, please set `dwURBBufferSize` of `FT_SetTransferParams` to 1024 for USB 3.0 port, and 512 for USB 2.0 port. This will make sure host URB requests return at the aligned boundary but leads to poor performance.

Throughput is around 165MiB/s for single channel read configuration when set to 1K, 362MiB/s when set to 32K.

4. Endpoint/Pipe ID vs FIFO ID

Endpoint or Pipe ID is used for `FT_ReadPipe()` and `FT_WritePipe()`. FT600/601 has 4 channels, the endpoint number is 0x2-0x5 for OUT pipes, and 0x82-0x85 for IN pipes.

FIFO ID is used for new APIs e.g. `FT_SetTransferParams()`, `FT_ReadPipeEx()`, `FT_WritePipeEx()`, `FT_ReadPipeAsync()` and `FT_WritePipeAsync()`, which is [0, 3] for FT600/FT601.